

# Complexity and simplicity of the climate feedbacks

Natalia Andronova, University of Michigan, [natand@umich.edu](mailto:natand@umich.edu)



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1. Feedbacks: exploration
2. Feedbacks: from models
3. Feedbacks: from observations

# 1. Feedbacks: exploration

Are we forcing the  
climate to change?



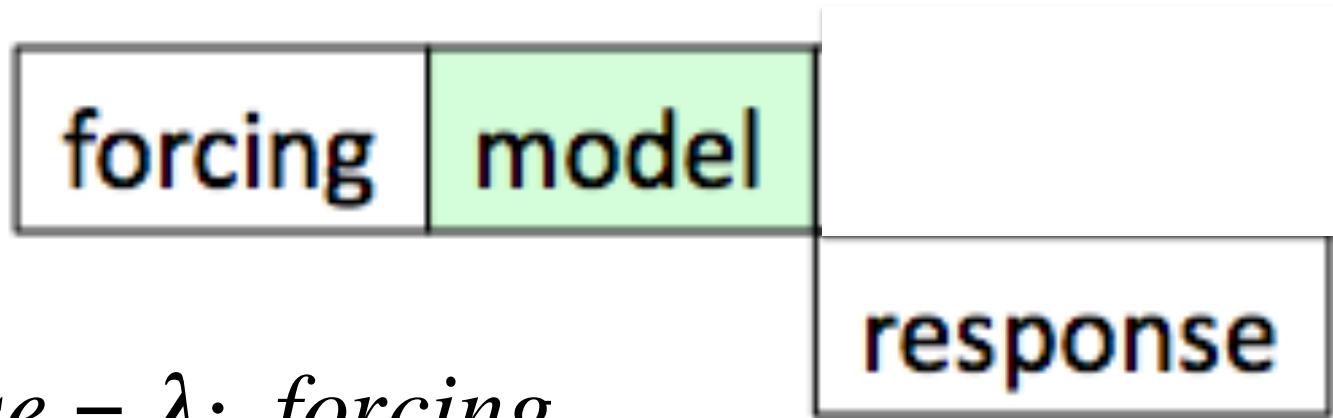
# 1. Feedbacks: exploration

Are we forcing the climate to change?



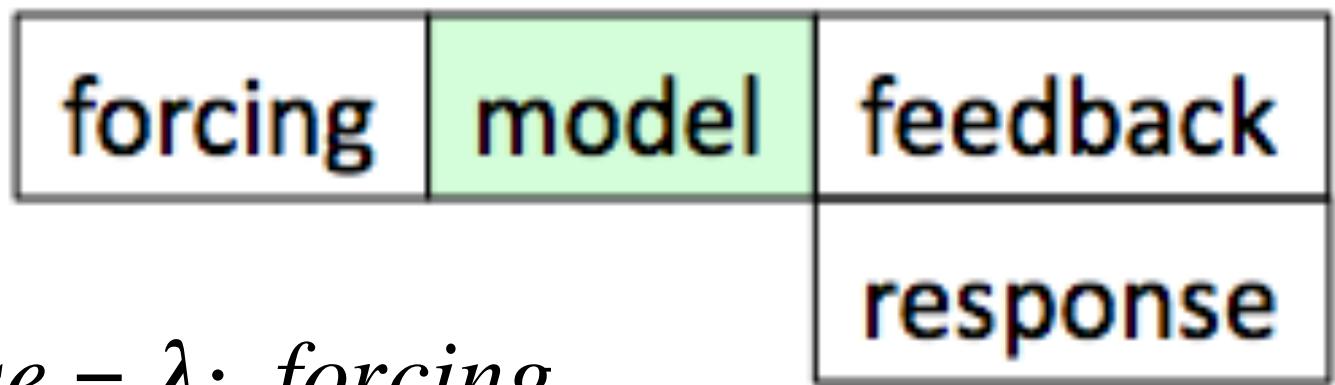
.... Or there is a feedback in the climate system which forces us to change?

## Q1: What is a feedback?



$$response = \lambda \cdot forcing$$

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$$response = \lambda \cdot forcing$$

$$response = \frac{pathway}{feedback} \cdot forcing$$

$$\frac{dA}{dt} = aA$$

$$\frac{dC}{dt} = cC + dA$$

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$$\frac{dC}{dt} = cC + dA$$



The system with No feedback between variables

$$\frac{dA}{dt} = aA$$

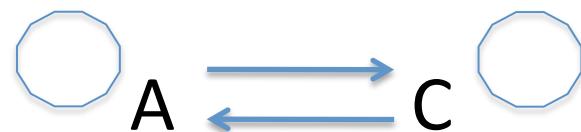


$$\frac{dC}{dt} = cC + dA$$

The system with No feedback between variables

The system with a feedback between A and C:

$$\frac{dA}{dt} = aA + cC$$



$$\frac{dC}{dt} = dA + eC$$

$$J = \begin{pmatrix} a & c \\ d & e \end{pmatrix}$$

How will J look with no self-feedbacks?

$$\frac{dA}{dt} = aA + cC$$

$$\frac{dC}{dt} = dA + eC$$

$$J = \begin{pmatrix} a & c \\ d & e \end{pmatrix}$$

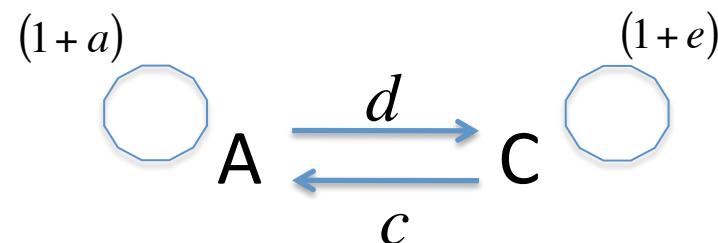
At an equilibrium point

$$0 = aA + cC$$

$$0 = dA + eC$$

$$A = (1+a)A + cC$$

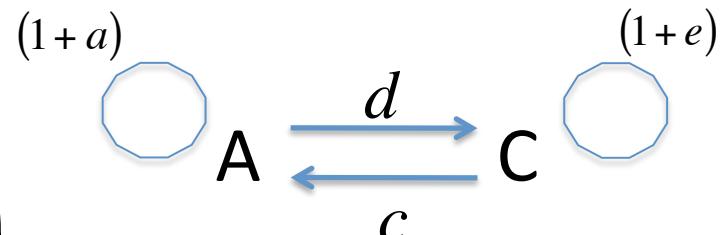
$$C = dA + (1+e)C$$



$$\frac{dA}{dt} = aA + cC$$

$$\frac{dC}{dt} = dA + eC$$

$$J = \begin{pmatrix} a & c \\ d & e \end{pmatrix}$$



$$A = (1+a)A + cC$$

$$C = dA + (1+e)C$$

$$\frac{dA}{dt} = aA + cC + F$$

$$\frac{dC}{dt} = dA + eC$$

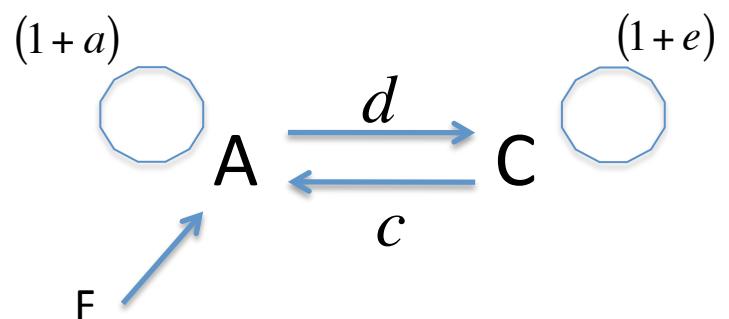
$$A = (1+a)A + cC + F$$

$$C = dA + (1+e)C$$

Find solution:

$$A = \frac{F}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

$$C = \frac{dF}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

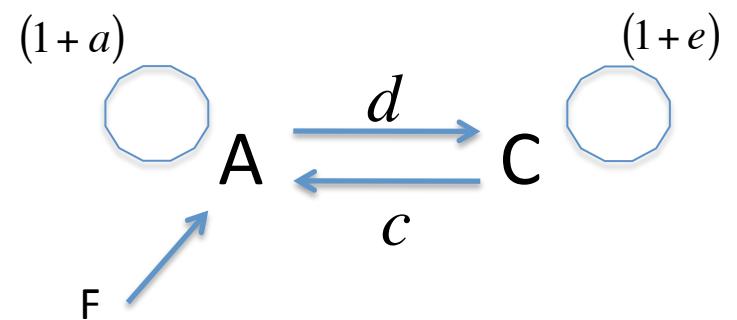


$$A = \frac{F}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

$$C = \frac{dF}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

$$A = \frac{F}{1 - L_{cd} - L_a - L_c + L_a L_c} = \frac{F}{1 - L}$$

$$C = \frac{d \cdot F}{1 - L_{cd} - L_a - L_c + L_a L_c} = \frac{d \cdot F}{1 - L}$$



(1-L) is total feedback effect

$$A = \frac{F}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

$$C = \frac{dF}{1 - cd - (1+a) - (1+e) + (1+a)(1+e)}$$

$$A = \frac{F}{1 - L_{cd} - L_a - L_c + L_a L_c} = \frac{F}{1 - L}$$

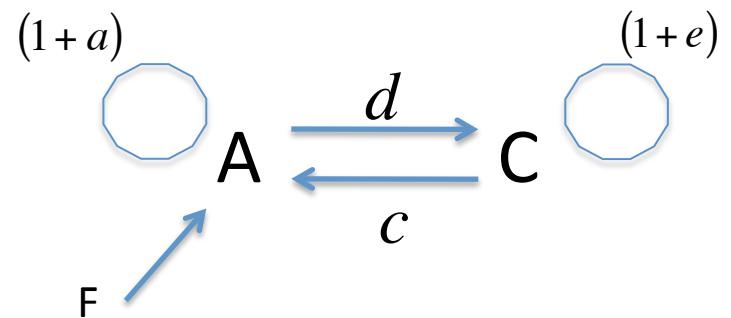
$$C = \frac{d \cdot F}{1 - L_{cd} - L_a - L_c + L_a L_c} = \frac{d \cdot F}{1 - L}$$

$$A(1 - L) = F$$

$$0 = -A(1 - L) + F$$

$$C(1 - L) = d \cdot F$$

$$0 = -C(1 - L) + d \cdot F$$



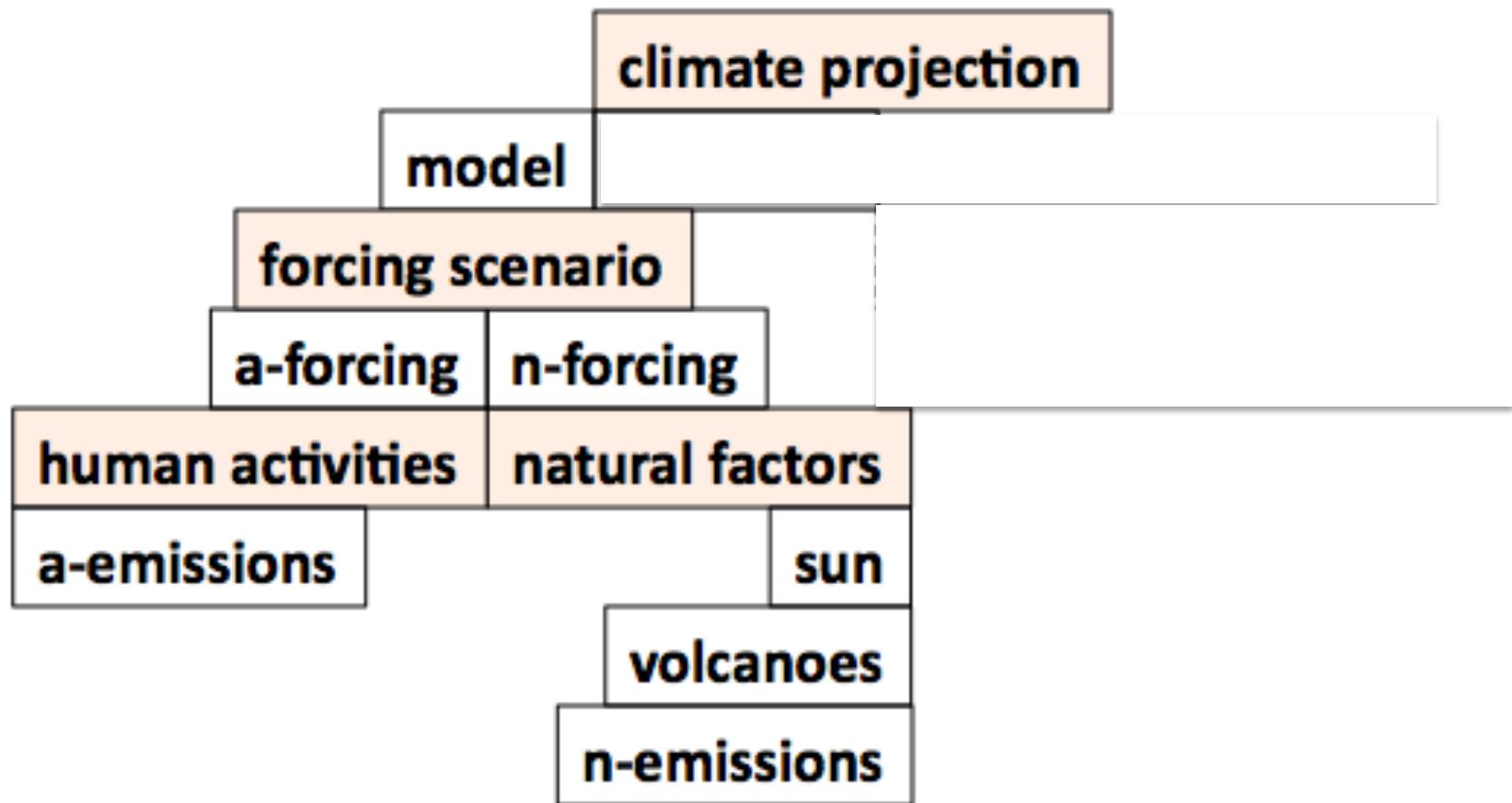
(1-L) is total feedback effect

$$\frac{dA}{dt} = -A(1 - L) + F$$

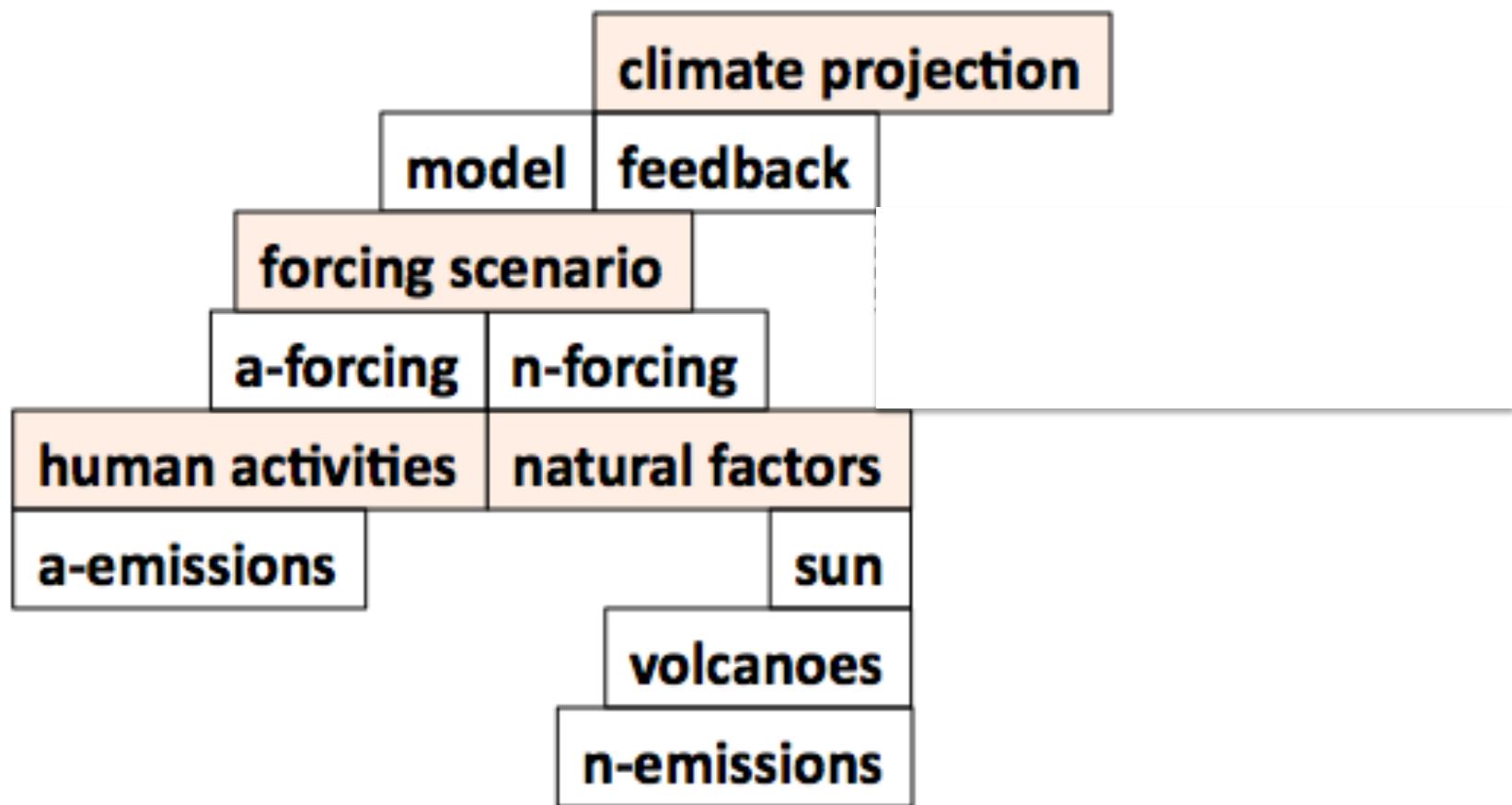
$$\frac{dC}{dt} = -C(1 - L) + d \cdot F$$

A and C are independent!

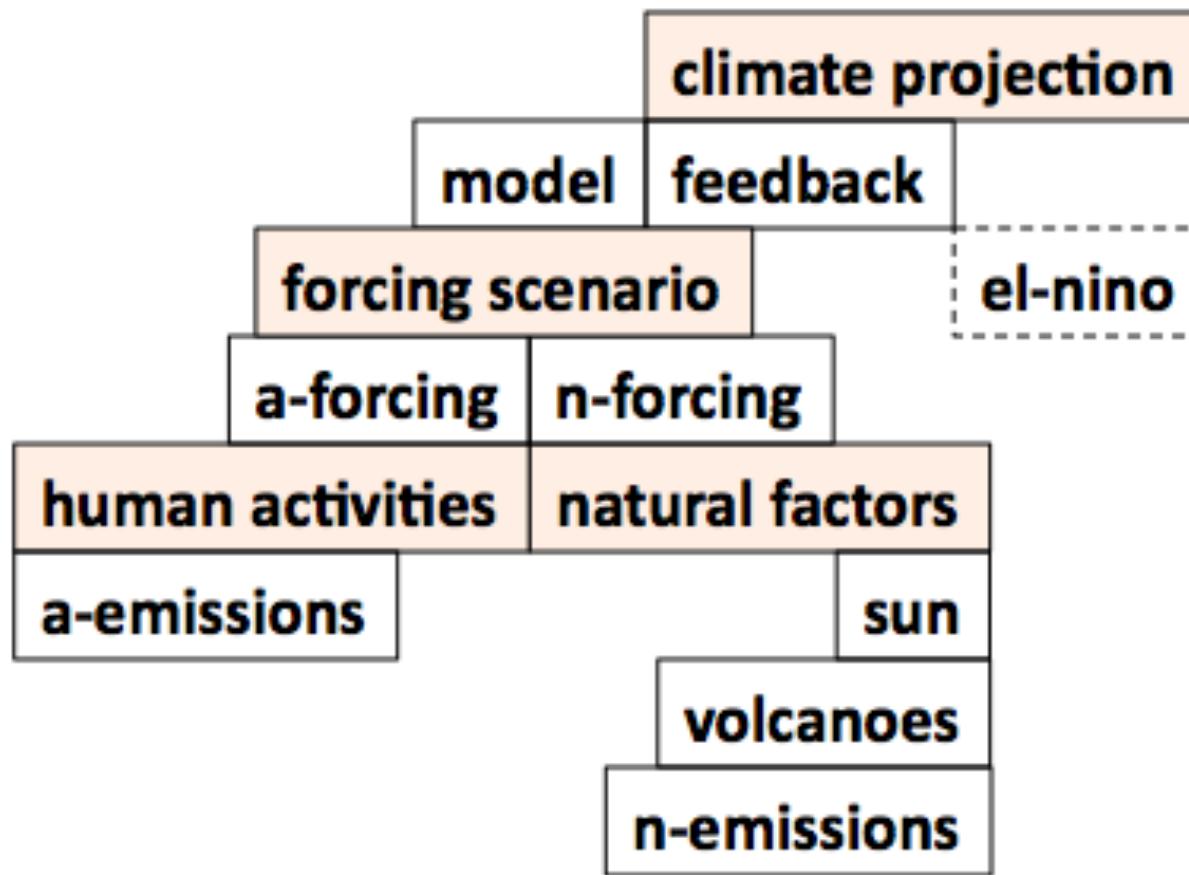
## 2. Feedbacks: from models



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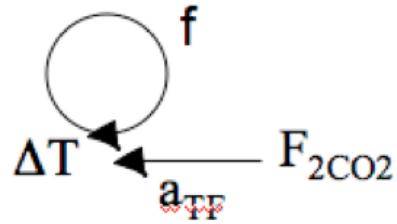


## 2. Feedbacks: from models

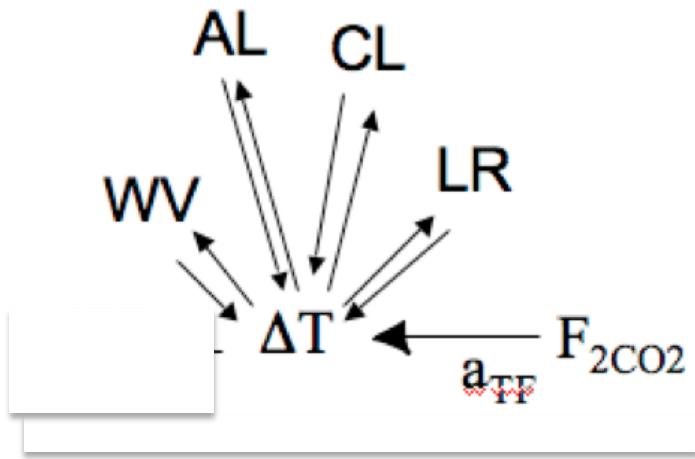
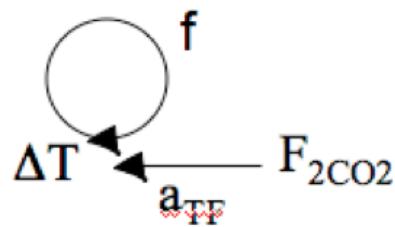


.... climate projection uncertainties should be also defined in terms of the uncertainties of climate feedbacks.

$$\Delta T_s = \frac{a_{TF}}{1-f} F_{2CO_2}$$

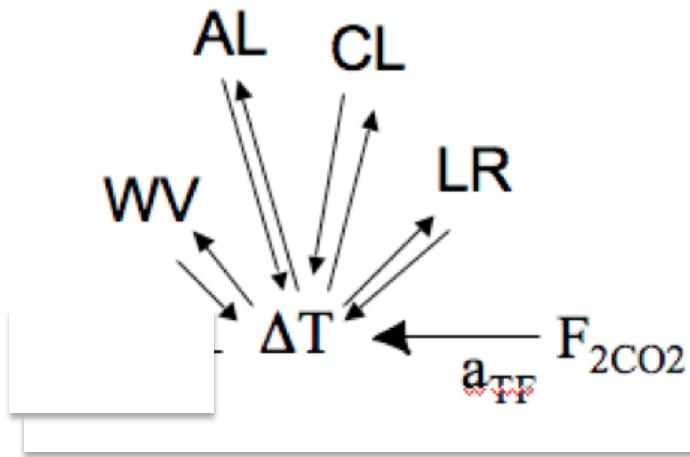
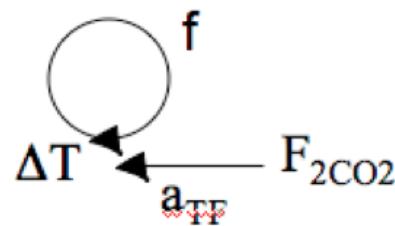


$$\Delta T_s = \frac{a_{TF}}{1-f} F_{2CO_2}$$



$$\begin{aligned}
 \Delta T_s &= \frac{a_{TF}}{1 - f_{TW} - f_{TC} - f_{TL} - f_{TA} - f_{TR}} F_{2CO_2} \\
 &= \frac{a_{TF}}{1 - a_{TW}a_{WT} - a_{TC}a_{CT} - a_{TL}a_{LT} - a_{TR}a_{RT}} F_{2CO_2} \\
 &= \frac{a_{TF}}{1 - f} F_{2CO_2}
 \end{aligned}$$

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$$\begin{aligned}\Delta T_s &= \frac{a_{TF}}{1 - f_{TW} - f_{TC} - f_{TL} - f_{TA} - f_{TR}} F_{2CO_2} \\ &= \frac{a_{TF}}{1 - a_{TW}a_{WT} - a_{TC}a_{CT} - a_{TL}a_{LT} - a_{TR}a_{RT}} F_{2CO_2} \\ &= \frac{a_{TF}}{1 - f} F_{2CO_2}\end{aligned}$$

$$G\Delta N = \lambda \Delta T_s \quad \Delta T \xrightleftharpoons[G]{\lambda} \Delta N \quad \lambda_x = \frac{\partial N}{\partial X} \frac{\Delta X}{\Delta T_s}$$

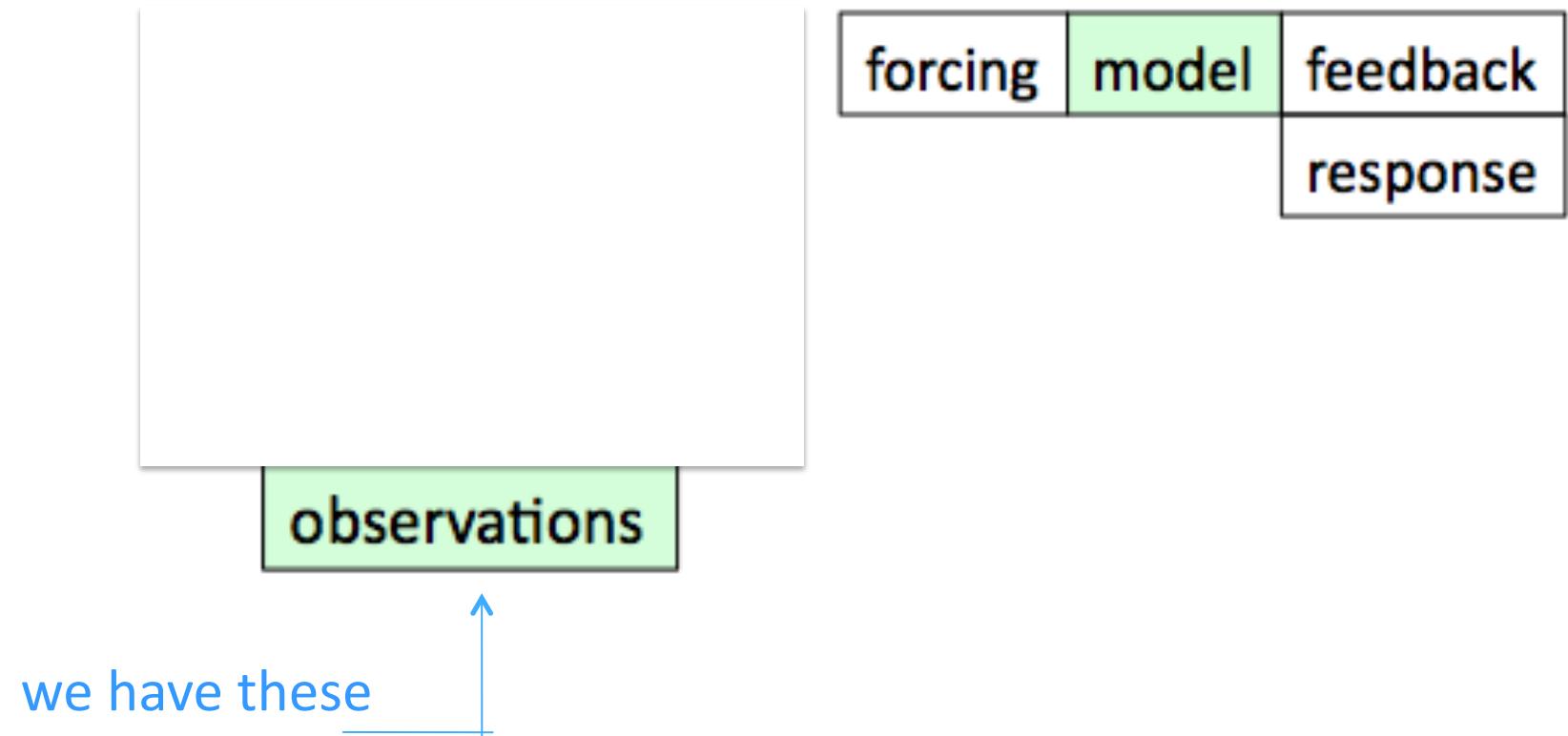
$$\lambda \Delta T_s = \left( \frac{\partial N}{\partial WV} \Delta WV + \frac{\partial N}{\partial CL} \Delta CL + \frac{\partial N}{\partial T} \Delta T + \frac{\partial N}{\partial AL} \Delta AL \right)$$

radiative kernels

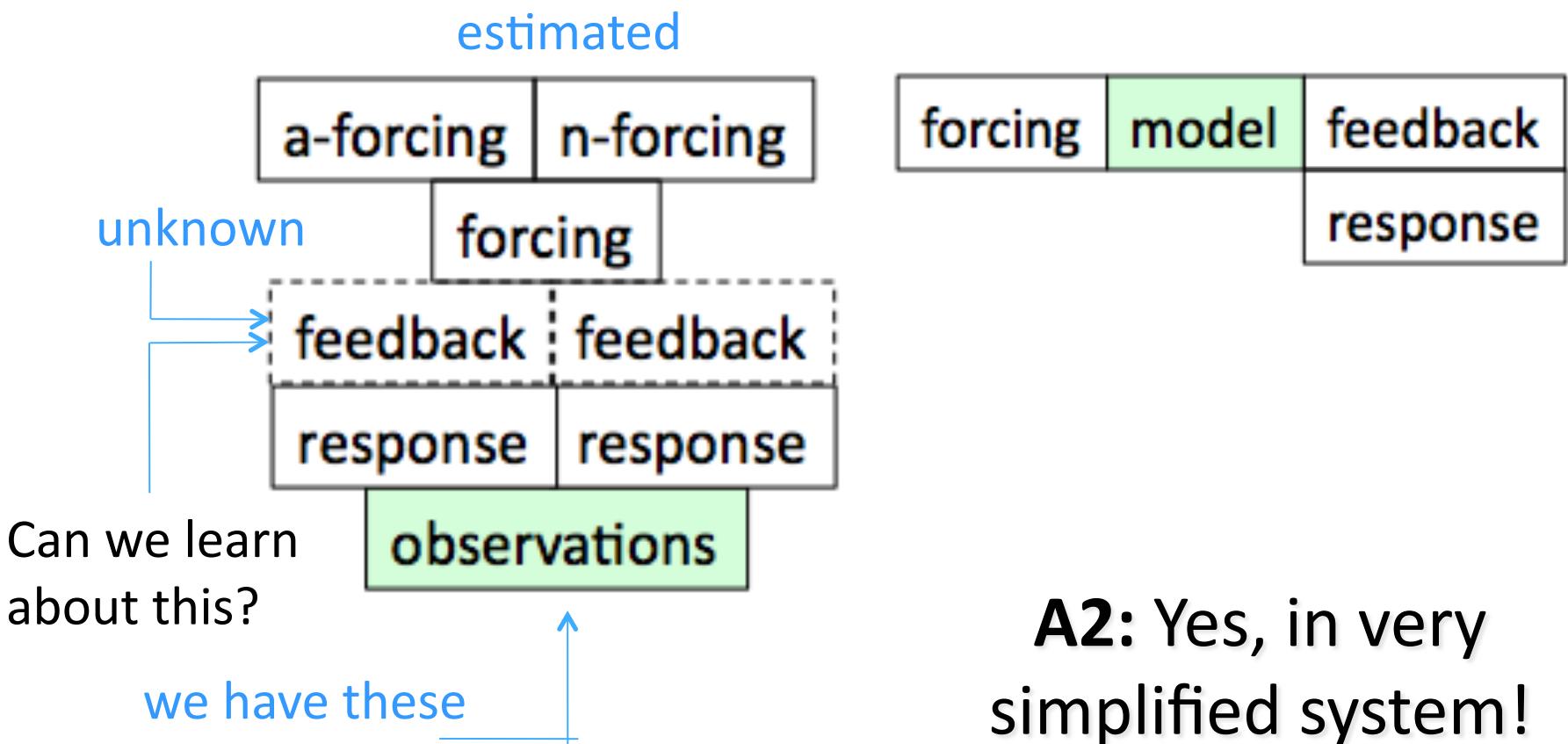
### 3. Feedbacks: from observations



## Q2: Is it possible to recognize feedbacks in the climate system solely through observations?



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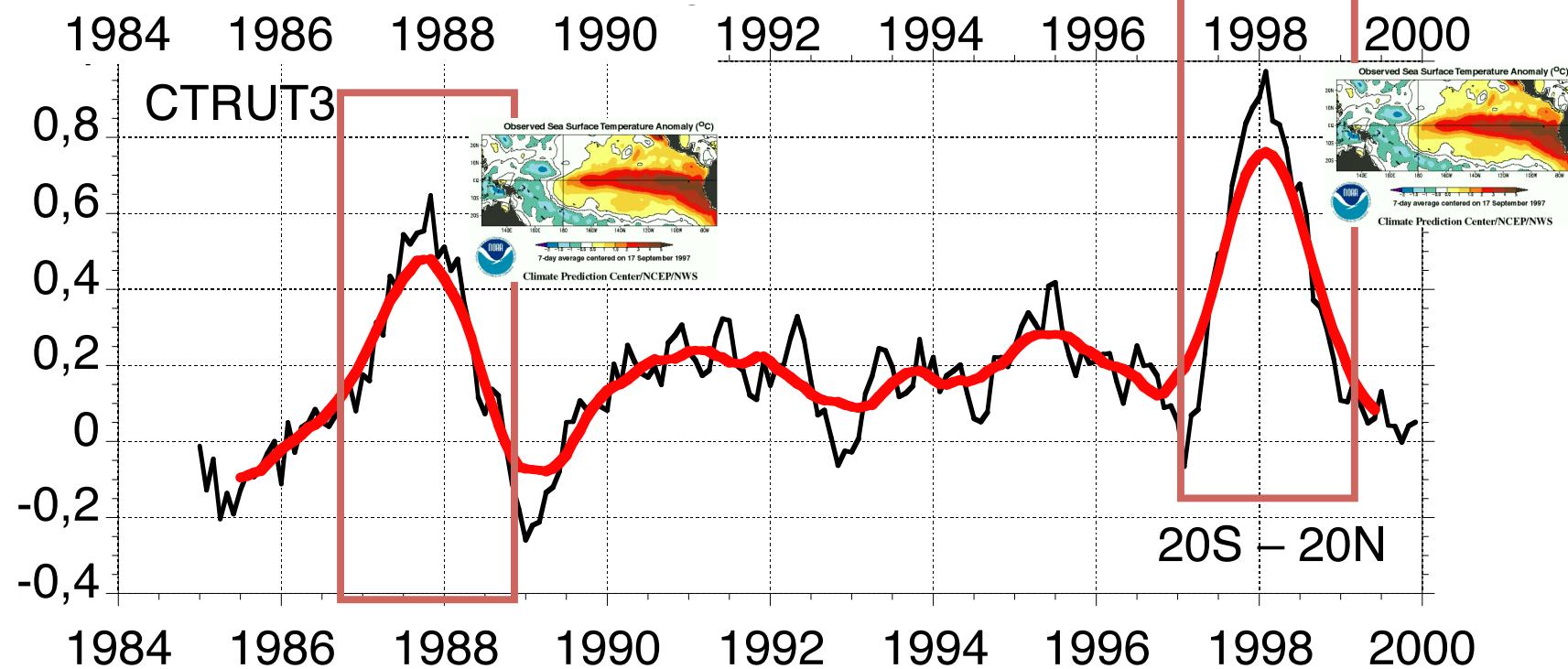
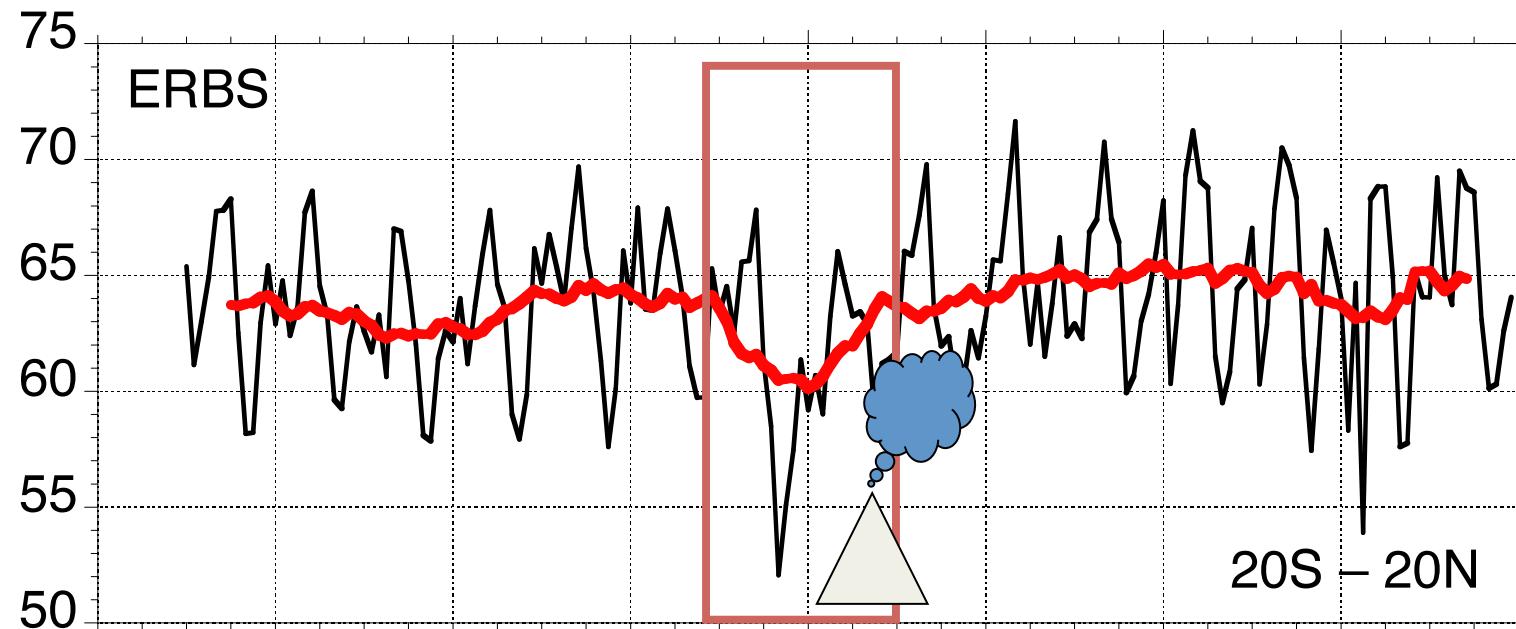


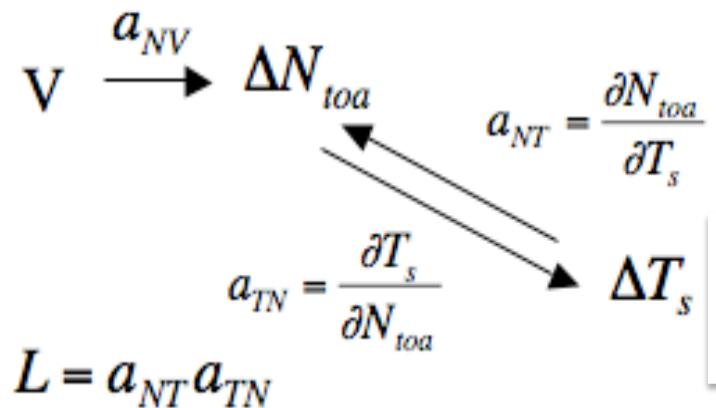
**A2: Yes, in very simplified system!**

*Andronova et al. (2009)*

$$\Delta N_{toa}$$
$$a_{NT} = \frac{\partial N_{toa}}{\partial T_s}$$
$$a_{TN} = \frac{\partial T_s}{\partial N_{toa}}$$
$$\Delta T_s$$
$$L = a_{NT} a_{TN}$$

$$response = \frac{pathway}{(1 - L)} forcing$$



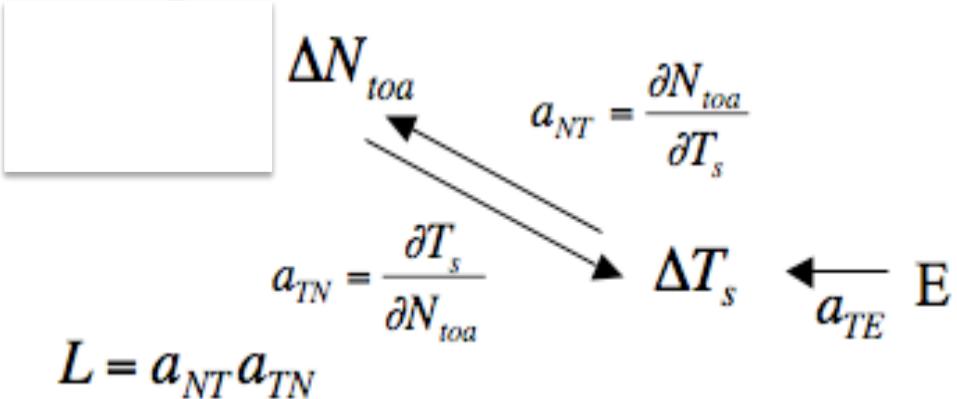


*response* =  $\frac{pathway}{(1 - L)}$  forcing

$$\Delta N_{toa} = \frac{1}{1-L} (a_{NV} V)$$

$$\Delta T_s = \frac{a_{TN}}{1-L} (a_{NV} V)$$

$$\frac{\Delta T_s}{\Delta N_{toa}} = a_{TN}$$



*response* =  $\frac{pathway}{(1 - L)}$  *forcing*

$$\Delta N_{toa} = \frac{1}{1-L} (a_{NV} V)$$

$$\Delta T_s = \frac{a_{TN}}{1-L} (a_{NV} V)$$

$$\frac{\Delta T_s}{\Delta N_{toa}} = a_{TN}$$

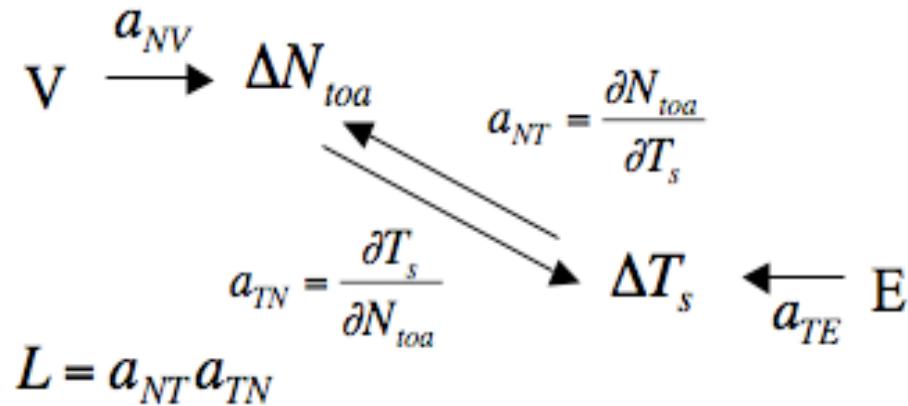
$$\Delta N_{toa} = \frac{a_{NT}}{1-L} (a_{TE} E)$$

$$\Delta T_s = \frac{1}{1-L} (a_{TE} E)$$

$$\frac{\Delta N_{toa}}{\Delta T_s} = a_{NT}$$

$$response = \frac{pathway}{(1 - L)} forcing$$

Total feedback effect

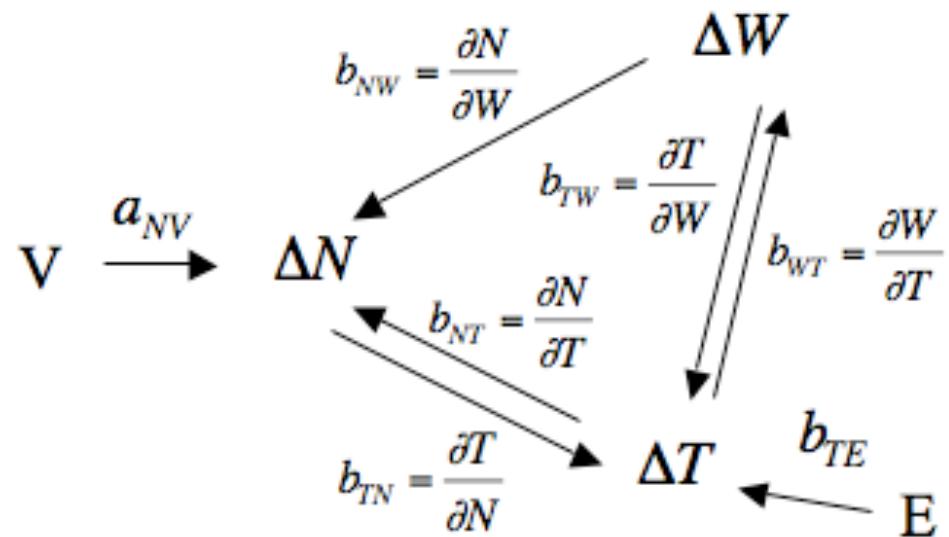
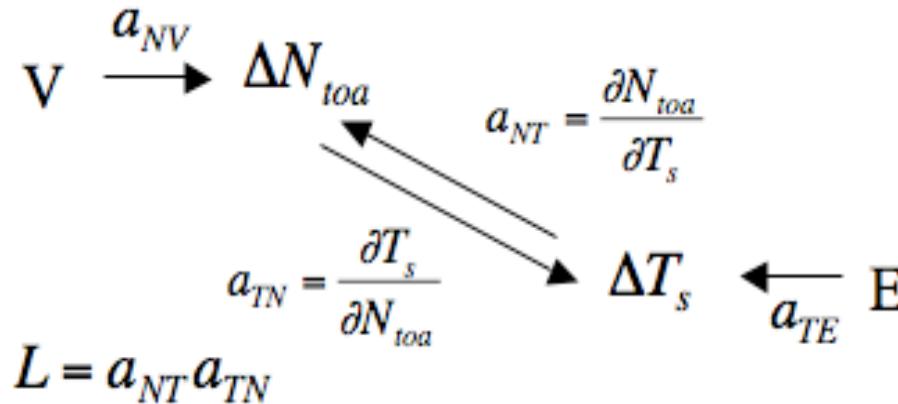


Name	$L = a_{TN} a_{NT}$
obs	$L = +0.020$ $a_{TN} = -0.0196$ $a_{NT} = -1.02$
M1	$L = +0.009$ $a_{TN} = -0.0086$ $a_{NT} = -1.08$
M2	$L = +0.067$ $a_{TN} = +0.0251$ $a_{NT} = +2.68$

Andronova et al. (2009)

$$response = \frac{pathway}{(1 - L)} forcing$$

Total feedback effect

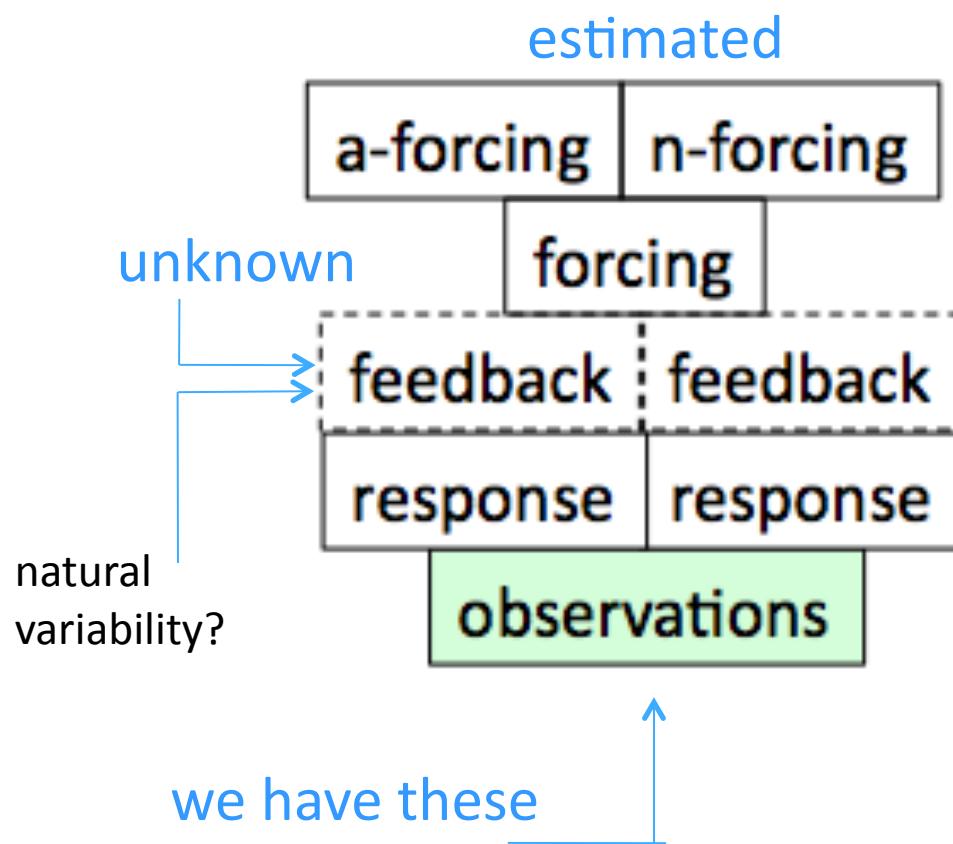


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$$L = L_{NT} + L_{WT} + L_{NWT}$$

Andronova et al. (2009)

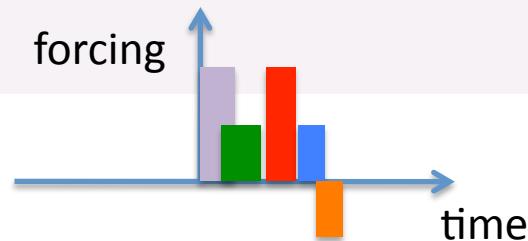
**Q3:** When compiling climate scenarios for the attribution of future climate, should we take into account the “natural variability” of the climate system?



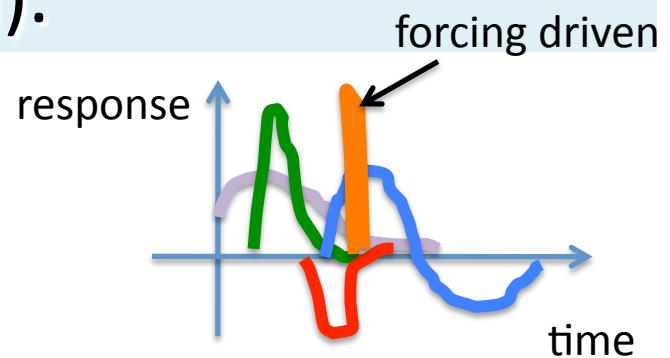
**A3:** We explore  
the answer next ...

1. The climate system is not in equilibrium, and its forcing is not constant.

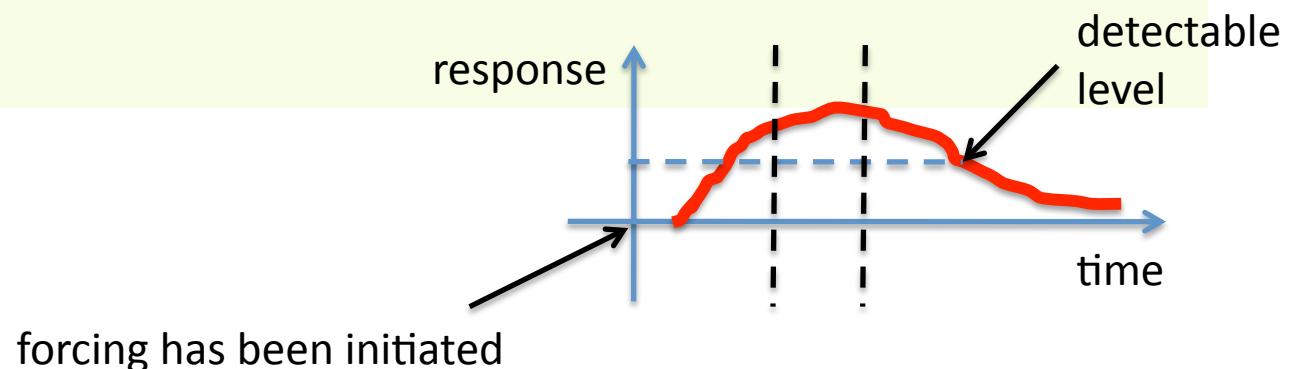
2. A transient forcing is a set of independent impulses.



3. All forcing “impulses” initiate independent responses (e.g. no synergism).

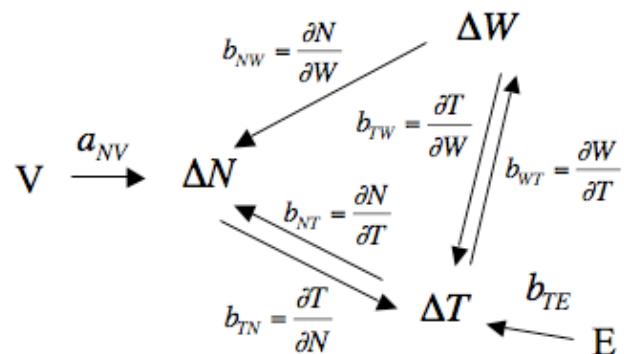


4. A feedback might be in place if lag between forcing and response exists. – “feedback driven system”.



5. We assume that a climate system's response to forcing is generated by the set of feedbacks, defined by the system's structural relationships.

$$response = \frac{pathway}{(1 - L)} forcing$$



We assume that in a system dominated by forcing, the system's response patterns are independent:

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

$$\text{Var}(X) * \text{Var}(Y) = (\text{rCov}(X, Y))^2$$

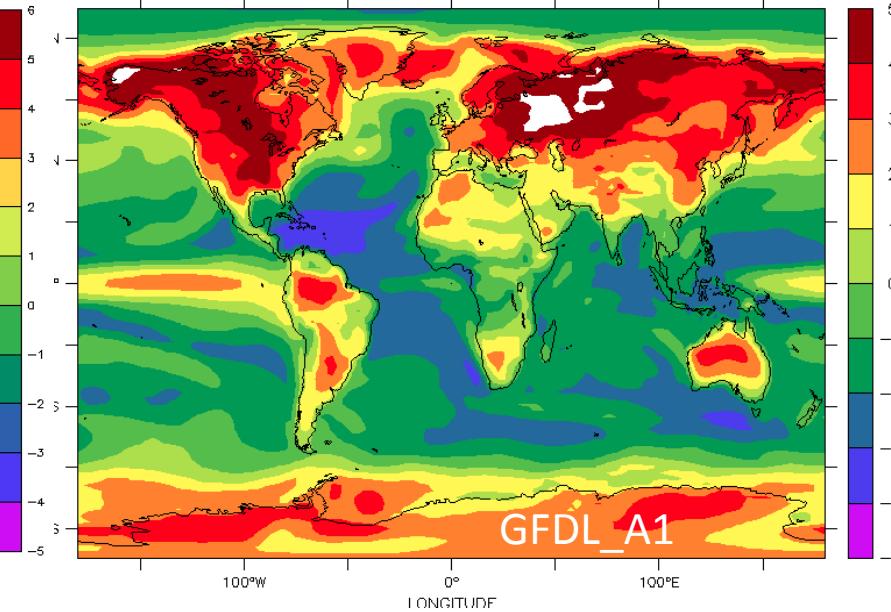
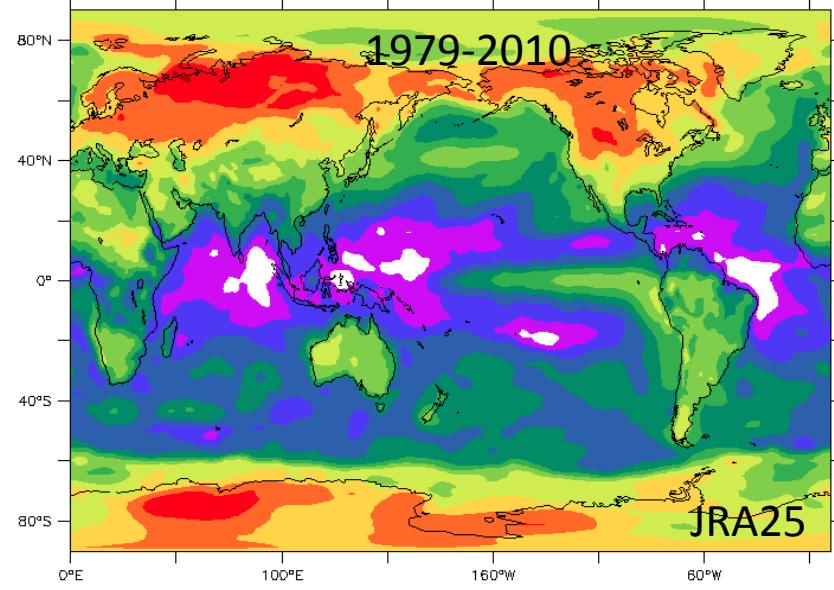
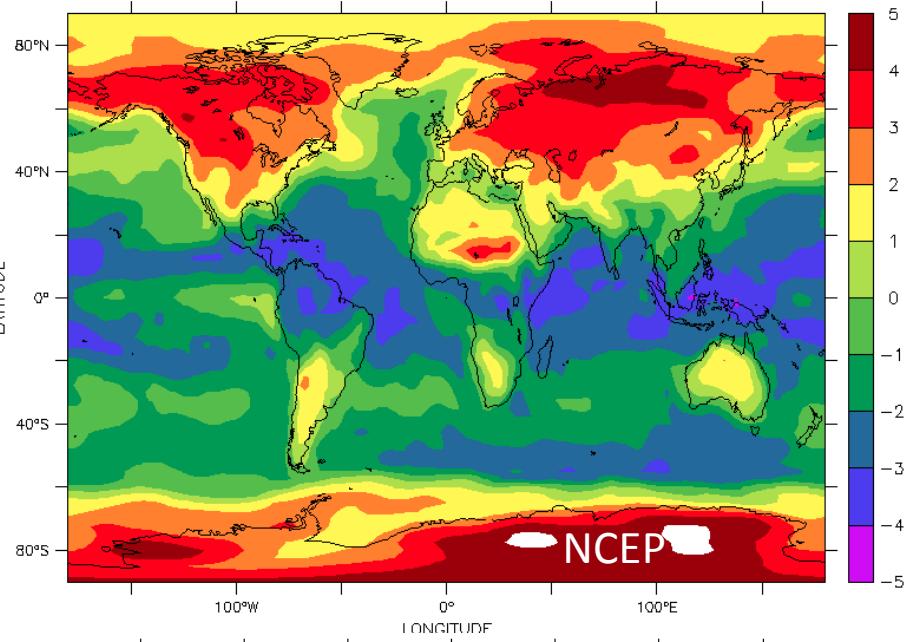
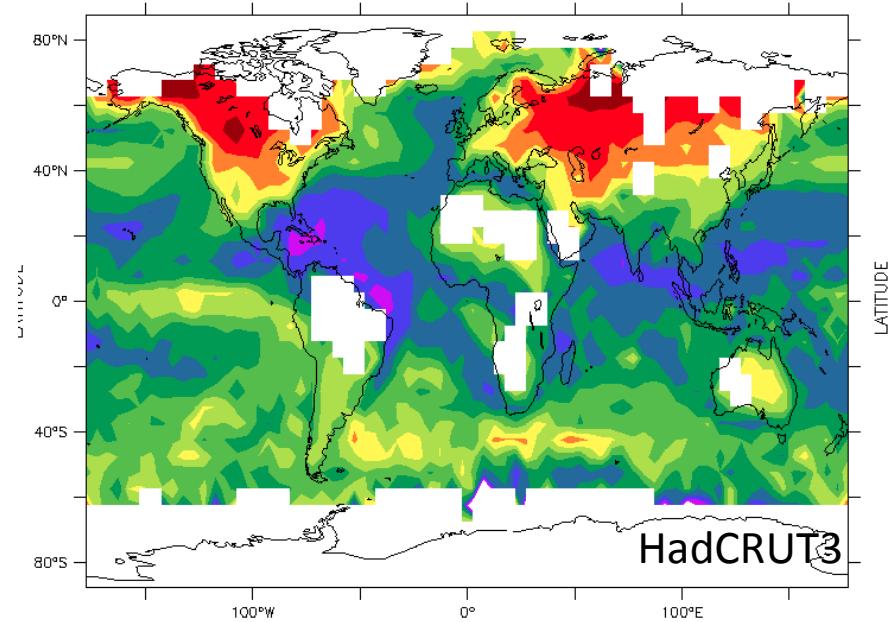
Forcing score derived from two responses:

$$\ln(\text{Var}(U_1) + \ln(\text{Var}(U_2)) = 2\ln(\text{rCov}(U_1, U_2))$$

$$\text{Cov}(U_1, U_2) \rightarrow 0;$$

$$\ln(\text{Var}(U_1) + \ln(\text{Var}(U_2)) \rightarrow -\infty$$

January-July 1948-2000



$$Var(\lambda F) = \lambda^2 Var(F)$$

response                          residual forcing

The ratio (R) of two response variability patterns represents the RF's tendency.

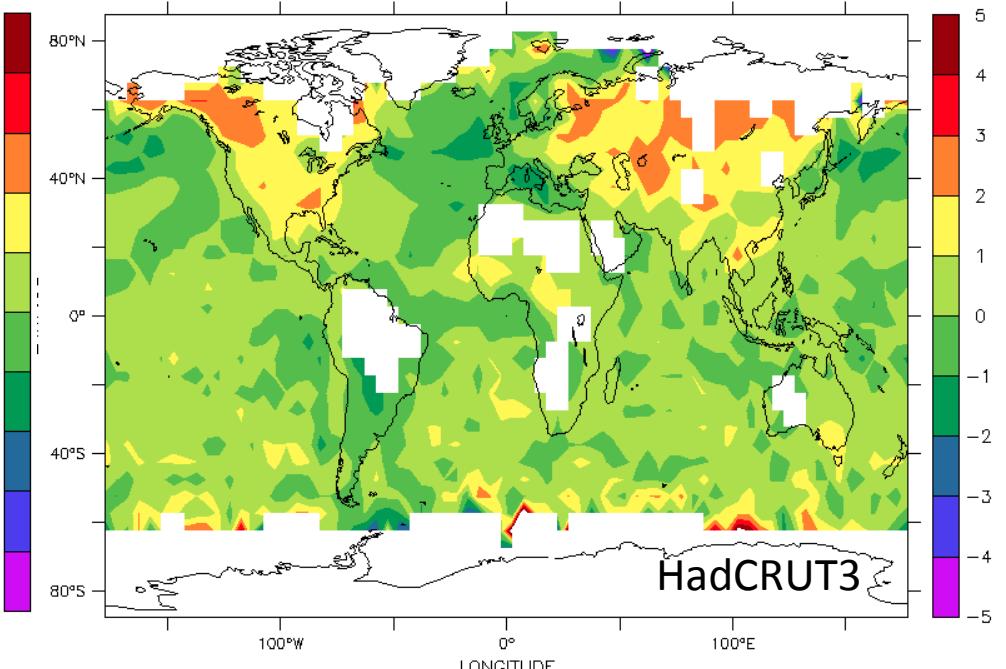
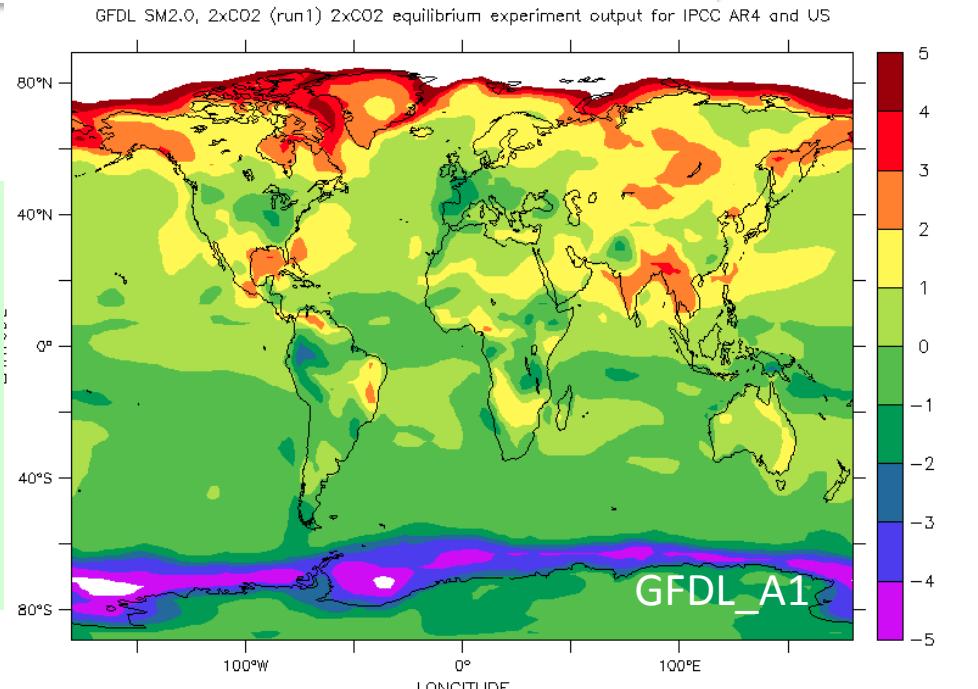
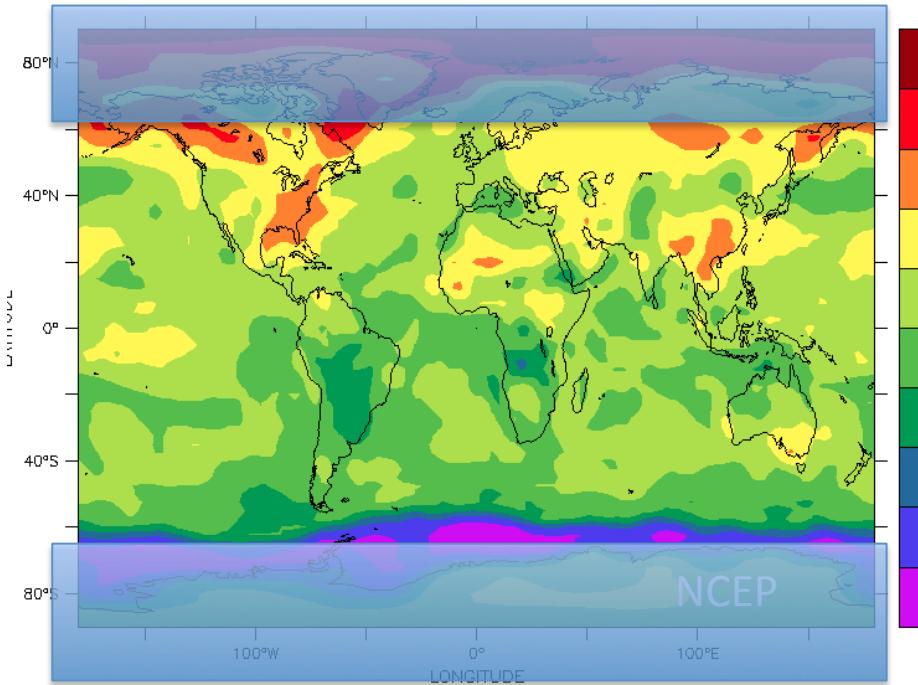
$$R \rightarrow 1 \Rightarrow \ln(Var(U_1)) - \ln(Var(U_2)) \rightarrow 0$$

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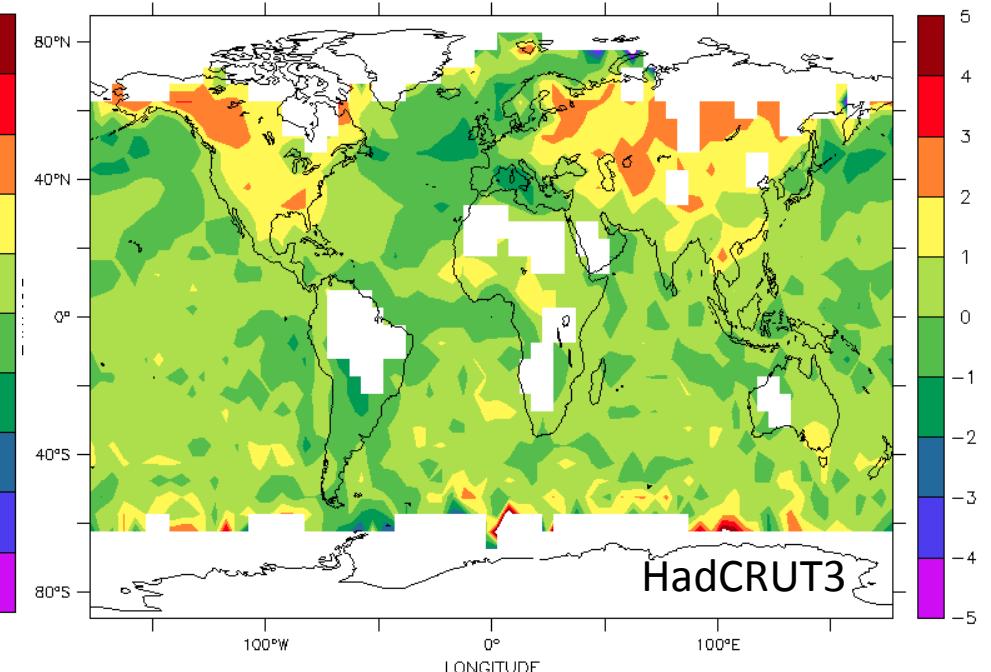
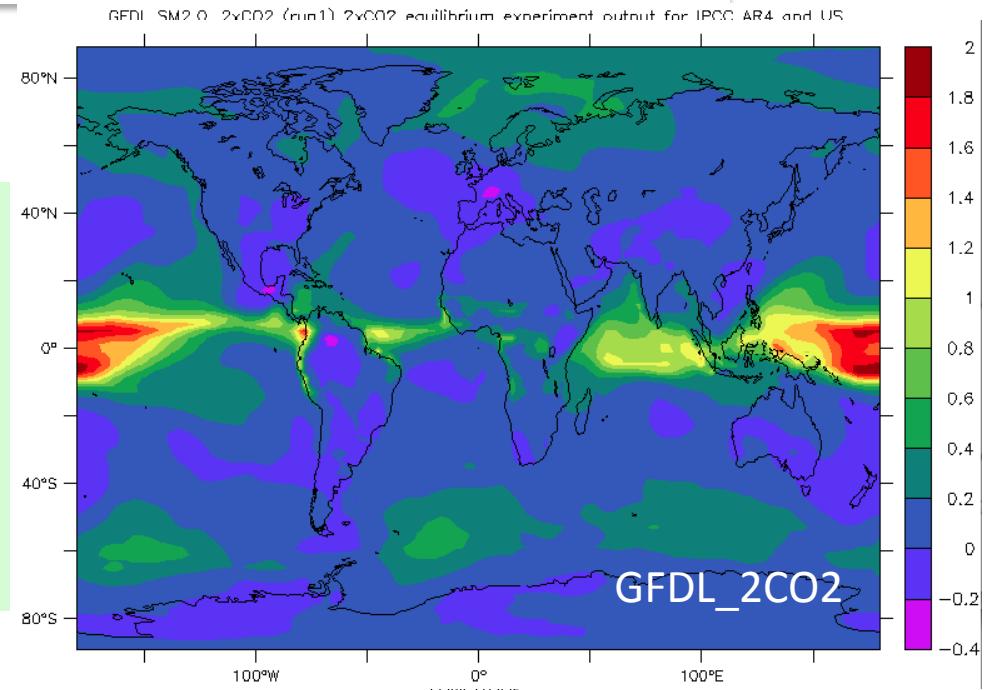
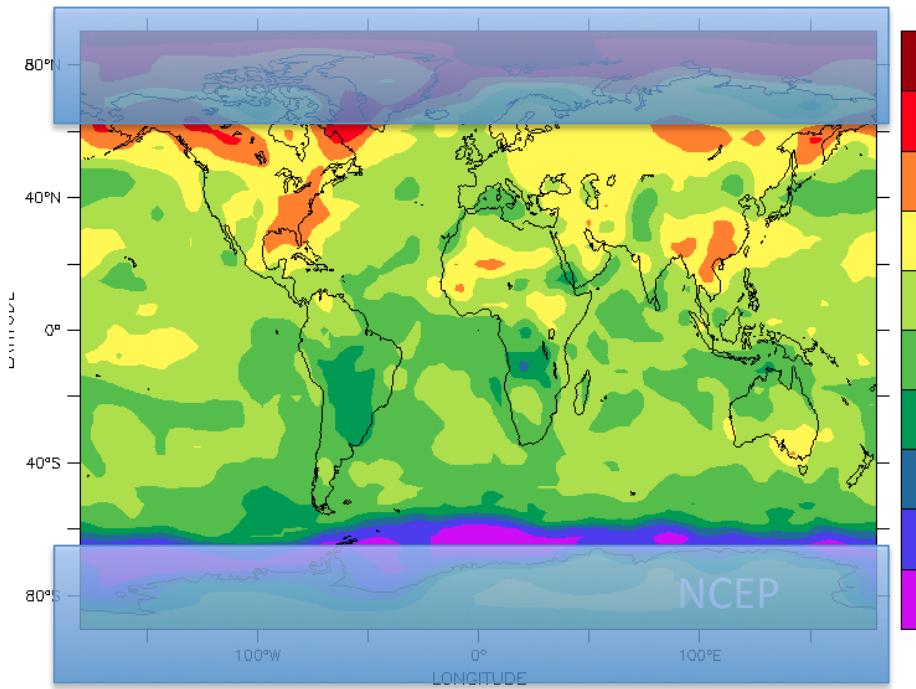


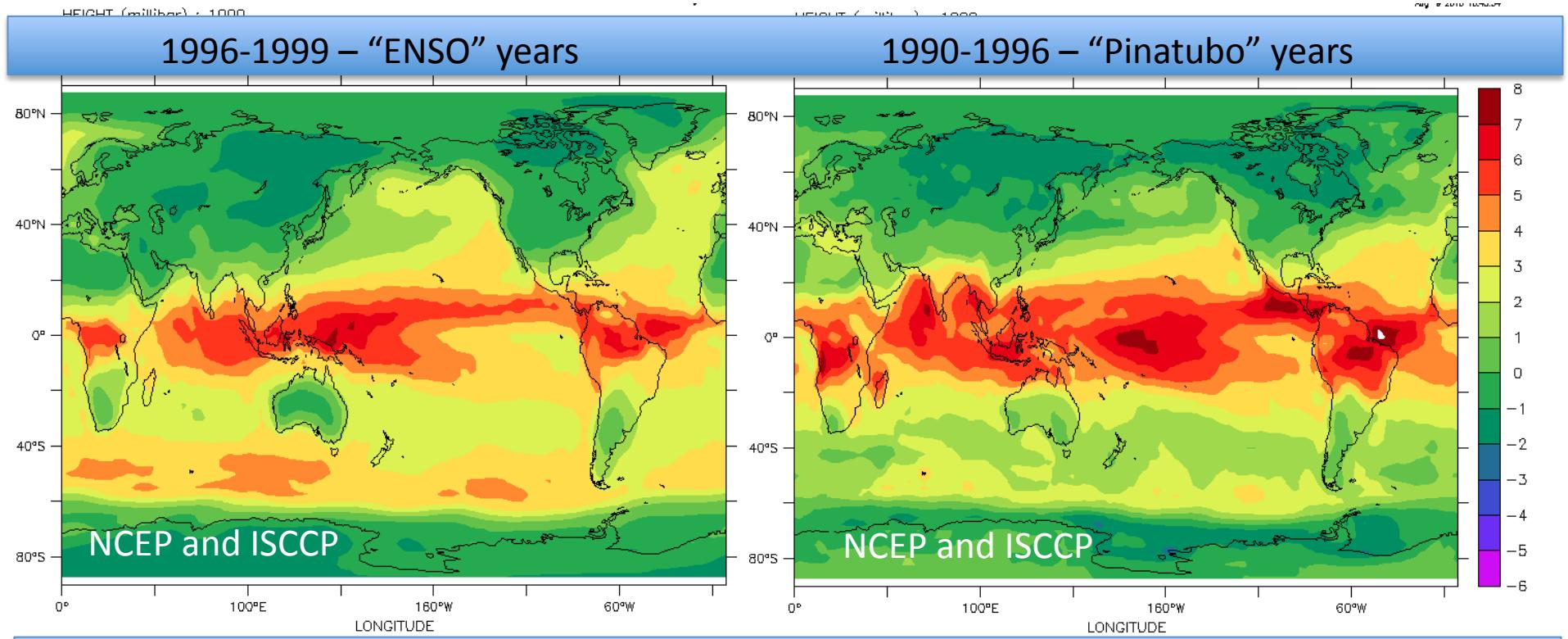
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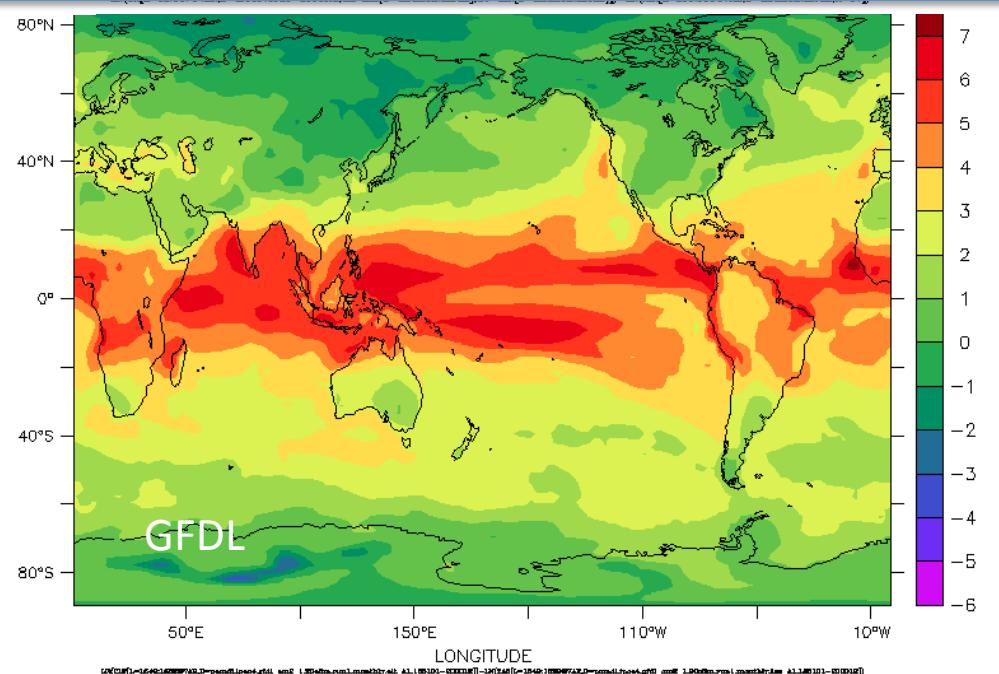
$$R \rightarrow 1 \Rightarrow \ln(Var(U_1)) - \ln(Var(U_2)) \rightarrow 0$$



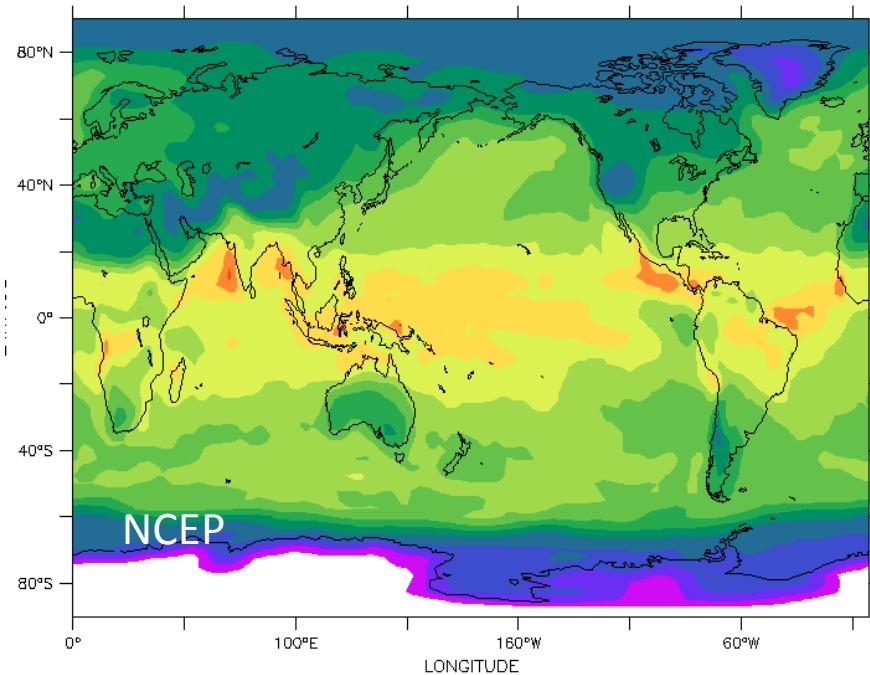


$$c_{CT} \sim \ln\left(\frac{Var(CL)}{Var(T_s)}\right)$$

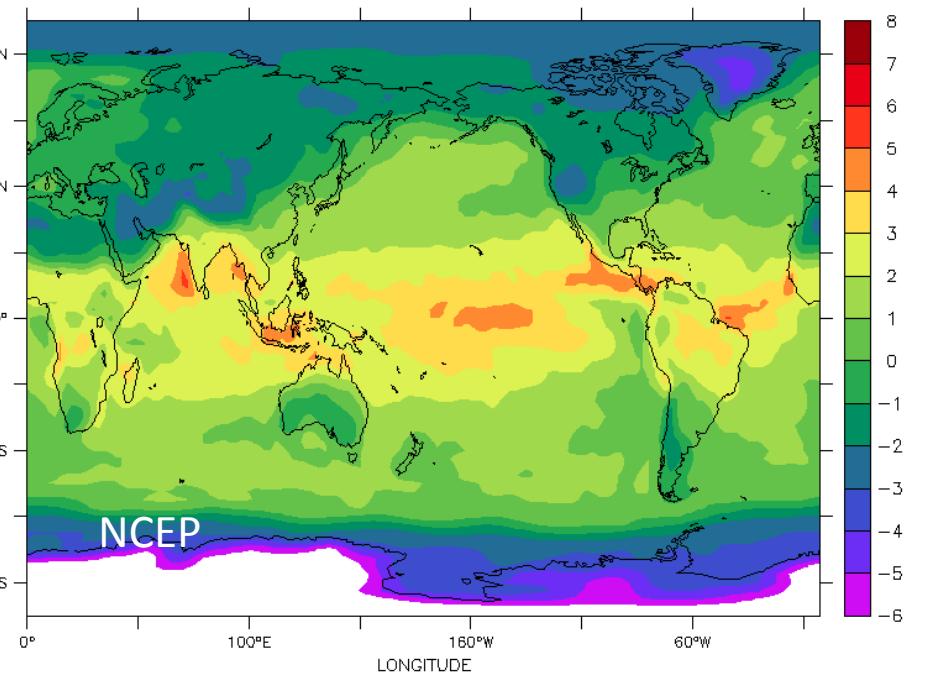
Other factors are at play if  $\ln() < 0$



## 1996-1999 – “ENSO” years

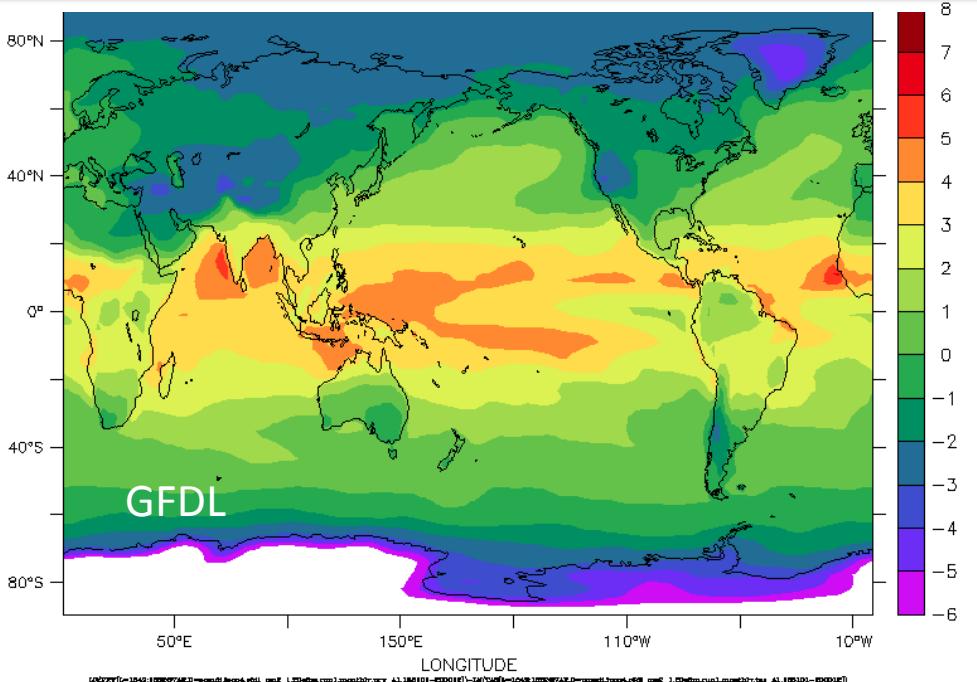


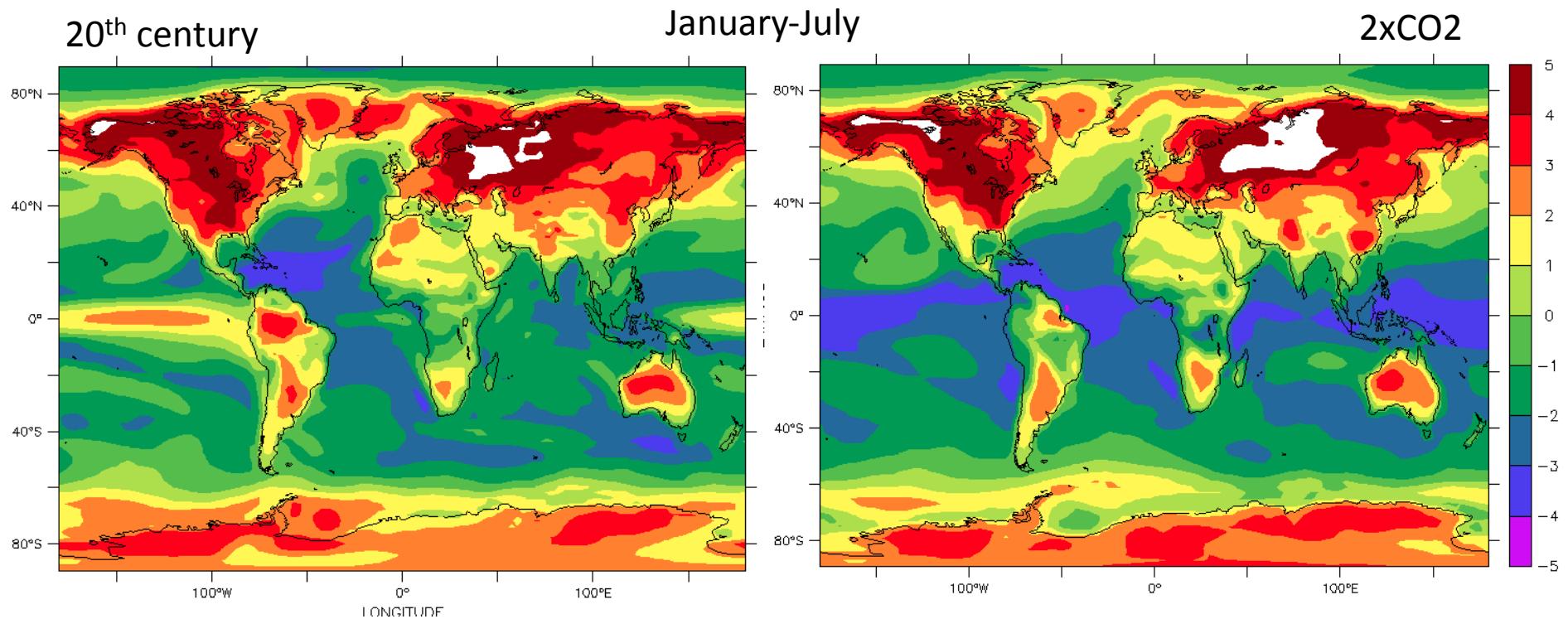
## 1990-1996 – “Pinatubo” years



$$c_{WT} \sim \ln\left(\frac{Var(W)}{Var(T_s)}\right)$$

Other factors are at play if  $\ln() < 0$





Thus, though one cannot separate individual feedbacks from observations, it is possible to determine whether feedback is or is not present.